



LCD PID Temperature Controllers

TX Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ⚠ symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.** (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use or store the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.**
Failure to follow this instruction may result in explosion or fire.
- 03. Install on a device panel to use.**
Failure to follow this instruction may result in fire or electric shock.
- 04. Do not connect, repair, or inspect the unit while connected to a power source.**
Failure to follow this instruction may result in fire or electric shock.
- 05. Check 'Connections' before wiring.**
Failure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit.**
Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.**
When connecting the sensor input and communication cable without dedicated cable, use AWG 24 to 16 cable for screwless type, use AWG 28 to 16 cable for screw type, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m for screw type.
Failure to follow this instruction may result in fire or malfunction due to contact failure.
- 02. Use the unit within the rated specifications.**
Failure to follow this instruction may result in fire or product damage
- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.**
Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.**
Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.

- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- 24 VAC~, 24-48 VDC≡ power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- LCD performance may vary depending on the usage environment. Check the environmental conditions, and do not install the device in places where direct sunlight or high temperatures may be present.
- This unit may be used in the following environments.
 - Indoors (in the environment condition rated in 'Specifications')
 - Altitude Max. 2,000 m
 - Pollution degree 2
 - Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

T	X	①	②	-	③	④	⑤	-	⑥
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① Display digits

4: 4 digit

② Size

N: DIN W 48 × H 24 mm
 S: DIN W 48 × H 48 mm
 SP: DIN W 48 × H 48 mm
 (11 pin plug type)
 M: DIN W 72 × H 72 mm
 W: DIN W 96 × H 48 mm
 H: DIN W 48 × H 96 mm
 L: DIN W 96 × H 96 mm

③ Option in/output

1: Alarm 1
 2: Alarm 1 + Alarm 2
 R: Alarm 1 + PV transmission
 T: Alarm 1 + RS485
 A: Alarm 1 + Alarm 2 + PV transmission
 B: Alarm 1 + Alarm 2 + RS485

④ Power supply

2: 24 VAC, 24-48 VDC
 4: 100 - 240 VAC

⑤ Control output

R: Relay
 S: SSR drive
 C: Selectable current or SSR drive output

⑥ Terminal type

None: Screw
 L: Screwless

Product Components

- Product (+ bracket)
- Instruction manual
- [TX4N] Terminal Protection Cover × 1

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

■ DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Sold Separately

- Terminal protection cover: RSA / RMA / RHA / RLA-COVER
- Communication Converter: SCM-USP / SCM-38I / SCM-US48I / SCM-WF48

Specifications

Series		TX Series
Power supply	AC type	100 - 240 VAC ~ 50/60 Hz
	AC/DC type	24 VAC ~ 50/60 Hz, 24-48 VDC ≡
Permissible voltage range		90 to 110 % of rated voltage
Power consumption	AC type	≤ 8 VA
	AC/DC type	AC: ≤ 8 VA, DC: ≤ 5 W
Sampling period		50 ms
Input specification		
Control output		Relay 250 VAC ~ 3 A, 30 VDC ≡ 3 A, 1a
		SSR 13 VDC ≡ ± 3 V, ≤ 20 mA
		Current DC 4-20 mA or DC 0-20 mA (parameter), Load resistance: ≤ 500 Ω
Alarm output		Relay AL1/2: 250 VAC ~ 3 A 1a • TX4N AL2: 125 VAC ~ 0.3 A 1a
Option output	PV transmission	DC 4 - 20 mA (Load resistance: ≤ 500 Ω, Output Accuracy: ± 0.3% F.S.)
	RS485 Comm.	Modbus RTU
Display type		11 Segment (White, Green, Yellow), LCD type ⁰¹⁾
Control type		Heating, Cooling ON/OFF, P, PI, PD, PID Control
Hysteresis		1 to 100 (0.1 to 50.0) °C/°F
Proportional band (P)		0.1 to 999.9 °C/°F
Integral time (I)		0 to 9,999 sec
Derivative time (D)		0 to 9,999 sec
Control cycle (T)		0.5 to 120.0 sec
Manual reset		0.0 to 100.0%
Relay life cycle	Mechanical	≥ 5,000,000 operations
	Electrical	≥ 200,000 operations (resistance load: 250 VAC ~ 3 A)
Dielectric strength		Between the charging part and the case: 3,000 VAC ~ 50/60 Hz for 1 min
Vibration		0.75 mm amplitude at frequency 5 to 55Hz in each X, Y, Z direction for 2 hours
Insulation resistance		≥ 100 MΩ (500 VDC ≡ megger)
Noise immunity		± 2 kV square shaped noise (pulse width 1 μs) by noise simulator R-phase, S-phase
Memory retention		≈ 10 years (non-volatile semiconductor memory type)
Ambient temperature		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)
Ambient humidity		35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)
Protection structure		IP50 (Front panel, IEC standards)
Insulation type		Double or reinforced insulation (mark: □, dielectric strength between primary circuit and secondary circuit: 3 kV)
Certification ⁰²⁾		CE, ENEC, UL, VDE, IEC, ETL
Unit weight (packaged)		<ul style="list-style-type: none"> • TX4N: ≈ 81 g (≈ 147 g) • TX4S: ≈ 97 g (≈ 150 g) • TX4S-L: ≈ 95 g (≈ 148 g) • TX4SP: ≈ 93 g (≈ 122 g) • TX4M: ≈ 138 g (≈ 213 g) • TX4W: ≈ 132 g (≈ 198 g) • TX4H: ≈ 130 g (≈ 196 g) • TX4H-L: ≈ 136 g (≈ 201 g) • TX4L: ≈ 204 g (≈ 279 g)

01) When using the unit at low temperature (below 0°C), display cycle is slow.

02) Certifications may differ depending on the model. Check the Autonics website for specific certification information.

Communication Interface

■ RS485

Comm. protocol	Modbus RTU
Application standard	EIA RS485 compliance with
Maximum connection	31 units (address: 01 to 127)
Synchronous method	Asynchronous
Comm. method	Two-wire half duplex
Comm. effective range	≤ 800 m
Comm. speed	2,400 / 4,800 / 9,600 (default) / 19,200 / 38,400 bps (parameter)
Response time	5 to 99 ms (default: 20 ms)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default), Odd, Even
Stop bit	1 bit, 2 bit (default)

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

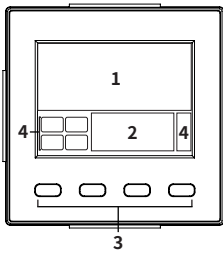
Input type	Decimal point	Display	Using range (°C)	Using range (°F)	
Thermo-couple	K (CA)	1	-50 to 1,200	-58 to 2,192	
		0.1	-50.0 to 999.9	-58.0 to 999.9	
	J (IC)	1	J I C.H	-30 to 800	-22 to 1,472
		0.1	J I C.L	-30.0 to 800.0	-22.0 to 999.9
	L (IC)	1	L I C.H	-40 to 800	-40 to 1,472
		0.1	L I C.L	-40.0 to 800.0	-40.0 to 999.9
T (CC)	1	T C.C.H	-50 to 400	-58 to 752	
	0.1	T C.C.L	-50.0 to 400.0	-58.0 to 752.0	
R (PR)	1	R P.R	0 to 1,700	32 to 3,092	
S (PR)	1	S P.R	0 to 1,700	32 to 3,092	
RTD	DPT100 Ω	1	d P L.H	-100 to 400	-148 to 752
		0.1	d P L.L	-100.0 to 400.0	-148.0 to 752.0
	Cu50 Ω	1	C U S.H	-50 to 200	-58 to 392
	0.1	C U S.L	-50.0 to 200.0	-58.0 to 392.0	

Display accuracy

Input type	Using temperature	Display accuracy
Thermocouple RTD	At room temperature (23°C ±5°C)	(PV ±0.3% or ±1°C higher one) ±1-digit • Thermocouple R, S below 200°C: (PV ±0.5% or ±3°C higher one) ±1-digit Over 200°C: (PV ±0.5% or ±2°C higher one) ±1digit • Thermocouple L, RTD Cu50 Ω: (PV ±0.5% or ±2°C higher one) ±1-digit
	Out of room temperature range	(PV ±0.5% or ±2°C higher one) ±1-digit • Thermocouple R, S: (PV ±1.0% or ±5°C higher one) ±1digit • Thermocouple L, RTD Cu50 Ω: (PV ±0.5% or ±3°C higher one) ±1digit

• In case of TX4SP Series, ±1°C will be added to the degree standard.

Unit Descriptions



- PV display part (White)**
 - Run mode: displays PV (Present value)
 - Setting mode: displays parameter name
- SV display part (Green)**
 - Run mode: displays SV (Setting value)
 - Setting mode: displays parameter setting value
- Input key**

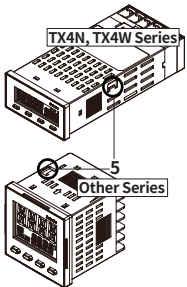
Display	Name
[MODE]	Mode key
[←], [↓], [▲]	Setting value control key

4. Indicator

Display	Name	Description
°C, %, °F	Unit	Displays selected unit (parameter)
AT	Auto tuning	Flashes during auto tuning every 1 sec
OUT1	Control output	Turns ON when control output 1 is ON • SSR output (cycle/phase control) MV over 5% ON • Current output MV over 5% ON
AL1/2	Alarm output	Turns ON when each alarm output is ON

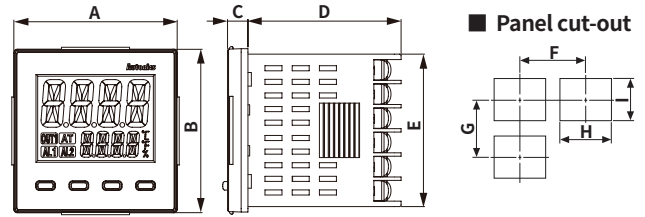
5. PC loader port:

For connecting communication converter (sold separately).
⚠ Do not drive with the loader port connected. Failure to follow this instruction may result in malfunction.



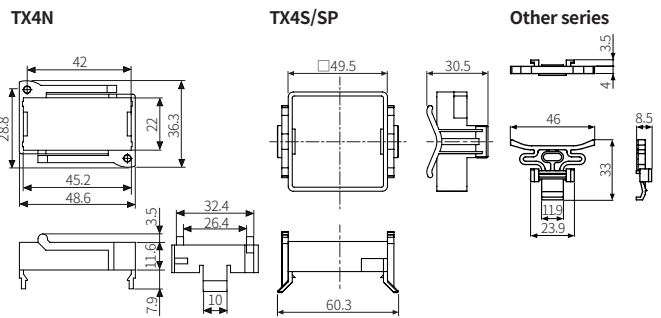
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TX4S Series.

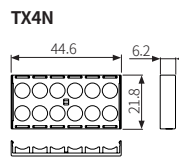


	Body					Panel cut-out			
	A	B	C	D	E	F	G	H	I
TX4N	48	24	4	94.2	21.8	≥ 55	≥ 37	45 ^{+0.6} ₀	22.2 ^{+0.3} ₀
TX4S	48	48	6	45	44.8	≥ 65	≥ 65	45 ^{+0.6} ₀	45 ^{+0.6} ₀
TX4S-L	48	48	6	54.6	44.8	≥ 65	≥ 65	45 ^{+0.6} ₀	45 ^{+0.6} ₀
TX4SP	48	48	6	67.1	44.8	≥ 65	≥ 65	45 ^{+0.6} ₀	45 ^{+0.6} ₀
TX4M	72	72	6	45	67.5	≥ 90	≥ 90	68 ^{+0.7} ₀	68 ^{+0.7} ₀
TX4W	96	48	6	45	44.7	≥ 115	≥ 65	92 ^{+0.8} ₀	45 ^{+0.6} ₀
TX4H	48	96	6	45	91.5	≥ 65	≥ 115	45 ^{+0.6} ₀	92 ^{+0.8} ₀
TX4H-L	48	96	6	54.6	91.5	≥ 65	≥ 115	45 ^{+0.6} ₀	92 ^{+0.8} ₀
TX4L	96	96	6	45	91.5	≥ 115	≥ 115	92 ^{+0.8} ₀	92 ^{+0.8} ₀

Bracket

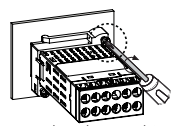


Terminal protection cover



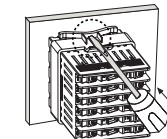
Installation Method

TX4N



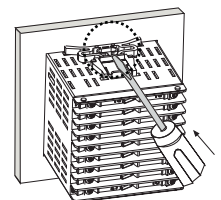
Crosshead screwdriver

TX4S/SP



Flathead screwdriver

Other series



Flathead screwdriver

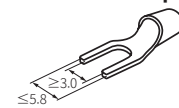
Mount the product to panel with bracket, push it to arrow direction by using screw driver.

- In case of TX4N Series, fasten the bolts.

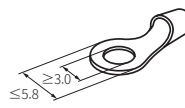
Terminal Specifications

- Unit: mm, Use the terminal of follow shape.

Screw: Crimp terminal

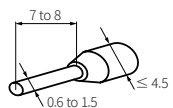


Fork crimp terminal



Round crimp terminal

Screwless: Wire ferrule



Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

	1. All display	2. Model	3. Input specification	4. Run mode
PV display part	0.0.0.0	t x 4 S	t x 4 S	α P E N
SV display part	0.0.0.0	2 4 R	K C R H	0

Errors

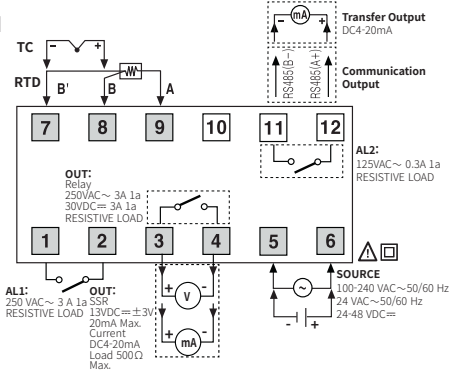
Display	Description	Troubleshooting
α P E n	Flashes when input sensor is disconnected or sensor is not connected.	Check input sensor status.
H H H H	Flashes when PV is higher than input range. ⁽¹⁾	When input is within the rated input range, this display disappears.
L L L L	Flashes when PV is lower than input range. ⁽¹⁾	

01) Be careful that when H H H H / L L L L error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type.

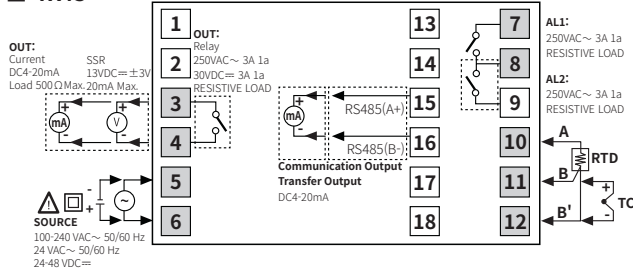
Connections

• Shaded terminals are standard model.

TX4N

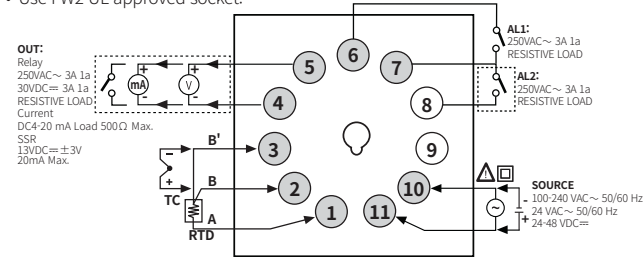


TX4S

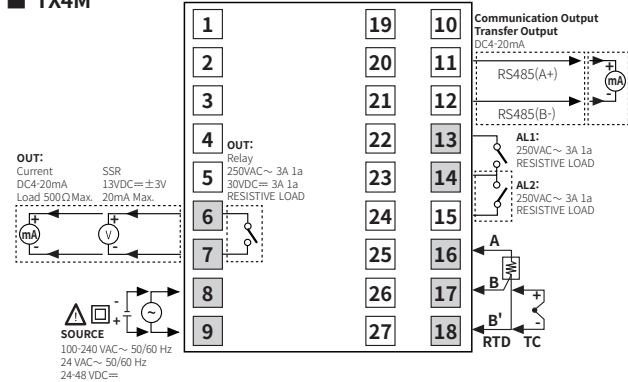


TX4SP

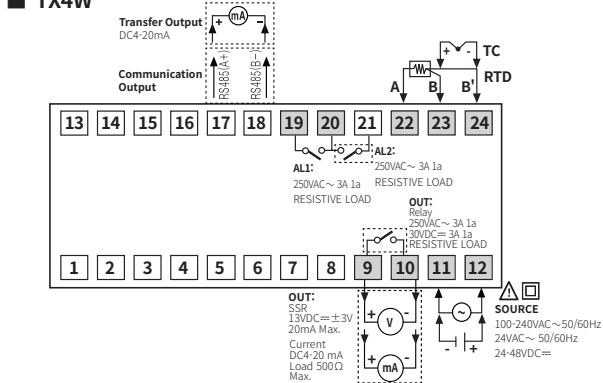
• Use FW2 UL approved socket.



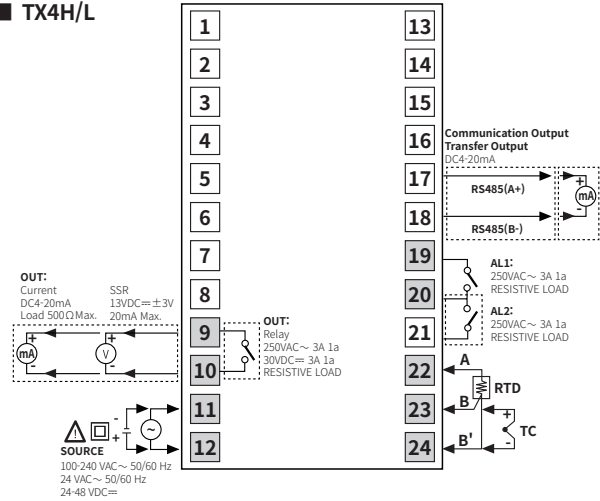
TX4M



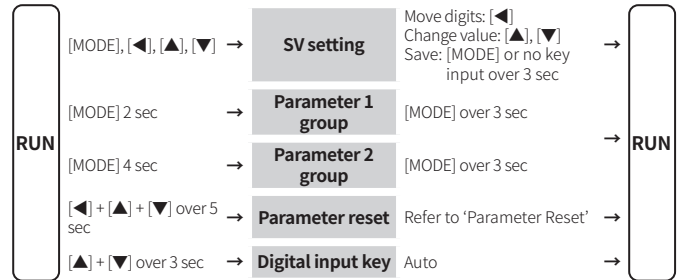
TX4W



TX4H/L



Mode Setting



Parameter Reset

01. Press the [◀] + [▲] + [▼] keys for over 5 sec. in run mode, INIT turns ON.
02. Change the setting value as YES by pressing the [▲], [▼] keys.
03. Press the [MODE] key to reset all parameter values as default and to return to run mode.

Parameter Setting

- Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the descriptions of each item.
- [MODE] key: Move to next item after saving / Return to RUN mode after saving (≥ 3 sec) / Return to previous parameter after saving (within 1 sec returning to RUN mode)
- [◀] key: Select parameter / Move digits / Return to the upper level without saving (≥ 2 sec) / Return to RUN mode without saving (≥ 3 sec)
- [▲], [▼] key: Select parameter / Change setting value
- Return to the upper level without saving when there is no key input for more than 30 seconds.
- The range in parentheses '(')' is the setting range when the set value of the 'input specification' parameter is used with one decimal point.
- Recommended parameter setting sequence: Parameter 2 group → Parameter 1 group → SV setting mode

Parameter 1 group

Parameter	Display	Default	Setting range	Condition
1-1 AL1 alarm temperature	AL 1	125.0	Deviation alarm: -F.S. to F.S. °C/°F Absolute value alarm: Within input range	2-16/19 AL1/2 alarm Operation:
1-2 AL2 alarm temperature	AL 2	125.0	[Alarm output2 model] Same as 1-1 AL1 alarm temperature	AM1 to AM6, HBA
1-3 Auto tuning	At	OFF	OFF: Stop, ON: Execution	-
1-4 Proportional band	P	10.0	0.1 to 999.9 °C/°F	-
1-5 Integral time	i	24.0	0 (OFF) to 9,999 sec	2-8 Control type: PID
1-6 Derivative time	d	4.9	0 (OFF) to 9,999 sec	-
1-7 Manual reset	RESt	5.0	0.0 to 100.0%	2-8 Control type: PID & 1-5 Integral time: 0
1-8 Hysteresis	HYSt	2	1 to 100 (0.1 to 50.0) °C/°F	2-8 Control type: ONOF

Parameter 2 group

Parameter	Display	Default	Setting range	Condition
2-1 Input specification ⁽⁰¹⁾	I N - t	# C R H	Refer to 'Input Type and Using Range'	-
2-2 Temperature unit ⁽⁰¹⁾	U N I t	° C	°C, °F	-
2-3 Input correction	I N - b	0	-999 to 999 (-199.9 to 999.9) °C/°F	-
2-4 Input digital filter	M A V F	0.1	0.1 to 120.0 sec	-
2-5 SV low limit ⁽⁰²⁾	L - S V	- 5 0	Within '2-1 Input specification: using range' L-SV ≤ H-SV - 1-digit °C/°F	-
2-6 SV high limit ⁽⁰²⁾	H - S V	1 2 0 0	H-SV ≥ L-SV + 1-digit °C/°F	-
2-7 Control output mode	o - F t	H E A T	HEAT: Heating, COOL: Cooling	-
2-8 Control type ⁽⁰³⁾	C - M d	P I d	PID, ONOF: ON/OFF	-
2-9 Control output	o U t	C U R R	[Selectable current or SSR drive output model] CURR: Current, SSR	-
2-10 SSR drive output type	S S R M	S t N d	[SSR drive output model] STND, CYCL, PHAS	-
2-11 Current output range	o M R	4 - 2 0	4-20: 4-20 mA, 0-20: 0-20 mA	2-9 Control output: CURR
2-12 Control cycle	t	2 0 0 (Relay) 2 0 (SSR)	0.5 to 120.0 sec	2-8 Control type: PID or 2-10 SSR drive output type: STND
2-13 AL1 alarm operation	AL - 1	AM 1 R □□□■	<input type="checkbox"/> AM0: Off <input type="checkbox"/> AM1: Deviation high limit alarm <input type="checkbox"/> AM2: Deviation low limit alarm <input type="checkbox"/> AM3: Deviation high, low limit alarm <input type="checkbox"/> AM4: Deviation high, low reverse alarm <input type="checkbox"/> AM5: Absolute value high limit alarm <input type="checkbox"/> AM6: Absolute value low limit alarm <input type="checkbox"/> SBA: Sensor break alarm <input type="checkbox"/> LBA: Loop break alarm (LBA)	-
2-14 AL1 alarm option		<input type="checkbox"/> A: Standard alarm <input type="checkbox"/> B: Alarm latch <input type="checkbox"/> C: Standby <input type="checkbox"/> D: Alarm latch and sequence 1 <input type="checkbox"/> E: Standby <input type="checkbox"/> F: Alarm latch and sequence 2 • Enter to option setting: Press [◀] key in 2-13 AL-1 alarm operation.	-	
2-15 AL2 alarm operation	AL - 2	AM 2 R	[Alarm output2 model]	-
2-16 AL2 alarm option			Same as '2-13/14 AL1 alarm operation/option'	-
2-17 Alarm output hysteresis	A H Y S	1	1 to 100 (0.1 to 50.0) °C/°F	2-13/14 AL1/2 alarm operation: AM1 to 6
2-18 LBA time	L b R t	0	0 (OFF) to 9,999 sec or auto ⁽⁰⁴⁾	2-13/14 AL1/2 alarm operation: LBA
2-19 LBA band	L b R b	2	0 (OFF) to 999 (0.0 to 999.9) °C/°F or auto ⁽⁰⁵⁾	2-13/14 AL1/2 alarm operation: LBA & 2-18 LBA time: > 0
2-20 Transmission output low limit	F 5 - L	- 5 0	[PV transmission output model] Refer to 'Input Type and Using Range'	-
2-21 Transmission output high limit	F 5 - H	1 2 0 0		-
2-22 Comm. address	A d R S	1	[Communication output model] 1 to 127	-
2-23 Comm. speed	b P S	9 6	[Communication output model] 24, 48, 96, 192, 384 (×100) bps	-
2-24 Comm. parity bit	P R t y	N o N E	[Communication output model] NONE, EVEN, ODD	-
2-25 Comm. stop bit	S t P	2	[Communication output model] 1, 2 bit	-
2-26 Response time	R S H t	2 0	[Communication output model] 5 to 99 ms	-
2-27 Comm. write	C o M W	E N A	[Communication output model] ENA: Enable, DISA: Disable	-
2-28 Digital input key	d i - k	S t o P	STOP: Stop control output, AL.RE: Alarm reset, AT*: Execute auto tuning, OFF	*2-8 Control type: PID
2-29 Sensor error, MV	E R M V	0 0	0.0: OFF, 100.0: ON	2-8 Control type: ONOF
2-30 Lock	L o C	o F F	OFF LOC1: Lock parameter 2 group LOC2: Lock parameter 1/2 group LOC3: Lock parameter 1/2 group, SV setting	2-8 Control type: PID

01) Below parameters are initialized when the setting value is changed.

- Parameter 1 group: AL1/2 alarm temperature,
- Parameter 2 group: Input correction, SV high/low limit, LBA band, Alarm output Hysteresis

02) If SV is lower/higher than low/high limit when the value is changed, SV is changed to the low/high limit value.

03) When changing the value from PID to ONOF, each value of following parameter is changed.
2-28 Digital input key: OFF, 2-29 Sensor error, MV: 0.0 (Setting value is lower than 100.0)

04) After auto tuning, the range is set as twice of the integral time automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.

05) After auto tuning, the range is set as 10% of the proportion band automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min value of the range.

Function: Alarm

000.0

Alarm operation Alarm option

Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Operation

• H: Alarm output hysteresis

Mode	Name	Alarm operation	Description
AM0	-	-	No alarm output
AM1	Deviation high limit		If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.
AM2	Deviation low limit		If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON.
AM3	Deviation high, low limit		If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.
AM4	Deviation high, low limit reverse		If deviation between PV and SV is higher than the lower limit deviation set value and less than the upper limit deviation set value, the alarm output will be ON.
AM5	Absolute value high limit		If PV is higher than the absolute value, the output will be ON.
AM6	Absolute value low limit		If PV is lower than the absolute value, the output will be ON.
SbR	Sensor break	-	It will be ON when it detects sensor disconnection.
LbR	Loop break	-	It will be ON when it detects loop disconnection.

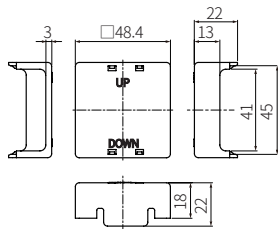
Option

Mode	Name	Description	Condition of reapply
A	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-
b	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status.	-
C	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Power ON
d	Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, alarm latch operates.	Power ON
E	Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.	Power ON, change SV, change alarm temperature / operation or change STOP to RUN mode
F	Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence 1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	Power ON, change SV, change alarm temperature / operation or change STOP to RUN mode

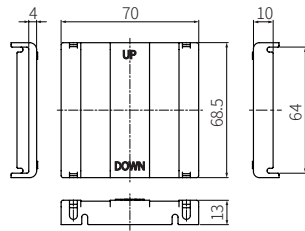
Sold Separately: Terminal Protection Cover

• Unit: mm, Only available for screw type models.

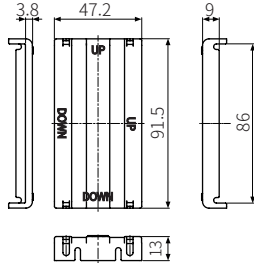
RSA-COVER: DIN W48 × H48



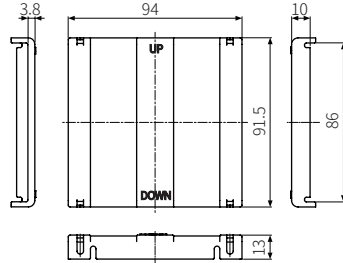
RMA-COVER: DIN W72 × H72



RHA-COVER: DIN W48 × H96



RLA-COVER: DIN W96 × H96



Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 Segment				11 Segment				12 Segment				16 Segment			
0	0	l	l	0	0	l	l	0	0	l	l	0	0	l	l
1	1	∩	J	1	1	∩	J	1	1	∩	J	1	1	∩	J
2	2	∩	K	2	2	∩	K	2	2	∩	K	2	2	∩	K
3	3	∩	L	3	3	∩	L	3	3	∩	L	3	3	∩	L
4	4	∩	M	4	4	∩	M	4	4	∩	M	4	4	∩	M
5	5	∩	N	5	5	∩	N	5	5	∩	N	5	5	∩	N
6	6	∩	O	6	6	∩	O	6	6	∩	O	6	6	∩	O
7	7	∩	P	7	7	∩	P	7	7	∩	P	7	7	∩	P
8	8	∩	Q	8	8	∩	Q	8	8	∩	Q	8	8	∩	Q
9	9	∩	R	9	9	∩	R	9	9	∩	R	9	9	∩	R
A	A	∩	S	A	A	∩	S	A	A	∩	S	A	A	∩	S
b	B	∩	T	b	B	∩	T	b	B	∩	T	b	B	∩	T
c	C	∩	U	c	C	∩	U	c	C	∩	U	c	C	∩	U
d	D	∩	V	d	D	∩	V	d	D	∩	V	d	D	∩	V
E	E	∩	W	E	E	∩	W	E	E	∩	W	E	E	∩	W
F	F	∩	X	F	F	∩	X	F	F	∩	X	F	F	∩	X
G	G	∩	Y	G	G	∩	Y	G	G	∩	Y	G	G	∩	Y
H	H	∩	Z	H	H	∩	Z	H	H	∩	Z	H	H	∩	Z