Autonics TCD210030AD



Wheel Type Incremental Rotary Encoders

ENC Series

PRODUCT MANUAL

Be sure to follow the instructions and precautions in the instruction manual, other manuals, and the Autonics website.

The specifications, dimensions, and other information in this document are subject to change without notice for product improvement. Certain models may be discontinued without notice.

Safety Precautions

- 'Safety Precautions' are provided to ensure safe and proper use of the product and to prevent accidents or hazards. Please make sure to follow them carefully.
- ▲ symbol indicates a caution, warning of potential hazards under certain conditions.

Marning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the product in applications that may cause serious injuries or property loss. (E.g. nuclear control systems, medical equipment, ships, vehicles, railroads, aircraft, combustion devices, safety devices, security systems, disaster prevention devices, etc.)
 Failure to do so may result in personal injury, property loss or fire.
- 02. Do not use or store the product in environments containing flammable, explosive, or corrosive gases, or in places exposed to high humidity, direct sunlight, radiant heat, vibration, shock, or salt. ailure to do so may result in explosion or f
- 03. Install the product on a device panel before use. Failure to do so may result in fire.
- 04. Do not connect, repair, or inspect the product while connected to a power

Failure to do so may result in fire.

- 05. Check the connection diagram before wiring.
- 06. Do not make any unauthorized modifications to the product. Failure to do so may result in fire.

▲ Caution Failure to follow instructions may result in injury or product damage.

- 01. Use the product within its rated specifications and performance limits. Failure to do so may result in fire or product damage
- 02. Do not short-circuit the load. Failure to do so may result in fire
- 03. Do not use the product near devices that generate strong magnetic fields or electrical noise, or in environments with strong alkaline or acidic

Failure to do so may result in product damage.

Cautions During Use

- Make sure to follow the instructions in 'Cautions During Use'. Failure to do so may result in unexpected accidents.
- Power input should be supplied from an isolated and limited voltage/current source, or from a Class 2 or SELV power supply..
- When using noise-generating devices (e.g. switching regulators, inverters, servo motors, etc.), ground the shielded wire to F.G.

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- When supplying power with an SMPS, ground the F.G. terminal and connect a noise suppression capacitor between the 0 V and F.G. terminals.
- To prevent surges and inductive noise, separate the wiring from high-voltage and power lines, and keep wiring lengths as short as possible.
- When extending wiring, check the cable type and response frequency, as line resistance and line-to-line capacitance may cause increased residual voltage or waveform distortion.
- This product may be used in the following environmental conditions.
- Indoors (within rated environmental performance specifications)
- Altitude: up to 2,000 m
- Pollution Degree 2
- Installation Category II

Cautions During Installation

- Install the product within the rated specifications in recommended usage environments.
- \bullet After securing the product and cable, do not pull with a force exceeding 30N.

Ordering Information

For reference only. The actual product does not support all combinations. To check all supported models, please refer to the Autonics website.

ENC 0 0 3 6 **②** Control output

1 Output phase

1: A, B

T: Totem-pole output N: NPN open collector output V: Voltage output

2 Min. measuring unit Power supply

1:1 mm 2:1 cm 3:1 m 4: 0.01 yd 5: 0.1 yd

5: 5 VDC ±5% 24: 12 - 24 VDC $\pm 5\%$

6 Connection

No mark: Axial cable type C: Axial cable connector type

Product Components

• Product

6:1 yd

· Instruction manual

Sold Separately

• M17 connector cable: CID6S-□

Connections

- Unused wires must be insulated.
- The metal case and shielded wire of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.

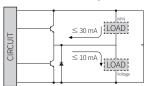
Ī	Pin	Color	Function	Pin	Color	Function
	1	Black	OUTA	4	Brown	+V
	2	White	OUTB	5	Blue	GND
	3	Orange	_	6	Shield	F.G.



Circuit Diagram

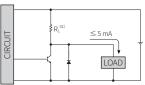
• Output circuits are identical for all output phases.

■ Totem-Pole Output



■ NPN Open Collector Output LOAD ≤ 30 mA

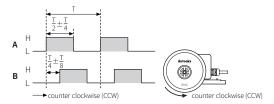
■ Voltage Output



01) [Power supply 12 - 24 VDC== model] 4.7 k Ω [Power supply 5 VDC== model] 820 Ω

Output Waveform

• Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T = 1 cycle of A)



Specifications

Model	ENC-1-□-T-□-□	ENC-1-□-N-□-□	ENC-1-□-V-□-□	
Min. measuring unit [/pulse]	1 mm/1 cm/1 m/0.01 yd/0.1 yd/1 yd models			
Control output	Totem-pole output	NPN open collector output	Voltage output	
Output phase	A, B	A, B	A, B	
Sink current	≤ 30 mA	≤ 30 mA	-	
Residual voltage	≤ 0.4 VDC==	≤ 0.4 VDC==	≤ 0.4 VDC==	
Source current	≤ 10 mA	-	≤ 5 mA	
Output voltage (5 VDC==)	≥ (V _{CC} - 2.0) VDC==	=	$\leq (\frac{R_L}{R_1 + R_1} \times V_{CC})$	
Output voltage (12 - 24 VDC==)	≥ (V _{cc} - 3.0) VDC==	-	VDC== 01)	
Response speed 02)	≤1 µs			
Max. response freq.	180 kHz			
Max. allowable revolution (3) 5,000 rpm				
Starting torque	Dependent on the coefficient of friction			
Unit weight	≈ 494 g			
Certification	C € ERE	C€ KERIE	C€ KEME	

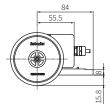
- 01) The output voltage varies depending on load resistance (R_L = load resistance).
- 02) Based on cable length: 2 m, I sink: 20 mA
 03) Select resolution to satisfy Max. allowable revolution ≥ Max. response revolution $[max. response revolution (rpm) = \frac{max. response frequency}{resolution} \times 60 sec]$

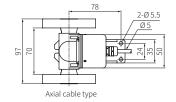
	EVDC + F0/ /			
Power supply	$5 \text{ VDC} = \pm 5\% \text{ (ripple P-P: } \leq 5\% \text{) /}$			
	12 - 24 VDC== ± 5% (ripple P-P: ≤ 5%) models			
Current consumption	≤ 80 mA (no load)			
Insulation resistance	\geq 100 M Ω (500 VDC== megger)			
Dielectric strength	Between charging part and case: 750 VAC \sim 50 / 60 Hz for 1 min.			
Vibration resistance	1 mm double amplitude at frequency 10 to 55 Hz in each X, Y, Z direction for 2 hours			
Shock resistance	≲75 G			
Ambient temp.	-10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation)			
Ambient humidity	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)			
Protection rating	IP50 (IEC standard)			
Connection	Axial cable type / cable connector type models			
Cable specification	Ø 5 mm, 4-wire, shielded cable cable type: 2 m, cable connector type: 250 mm			
Wire specification	AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm			
Connector specification	M17 6-pin plug type			

Dimensions

- Unit: mm (Refer to the CAD files from the Autonics website for exact dimensions)
- Cable type shown as reference.

Refer to 'Specifications' for detailed specifications of cable, wire and connector.





■ Min. Measuring Unit and Wheel Circumference

Min. measuring unit [/pulse]	Revolution wheel circumference	Pulse / 1 rotation of the encoder 01)	Gear ratio
1 mm		250	1:1
1 cm	250 mm	100	4:1
1 m		1	4:1
0.01 yd		100	4:1
0.1 yd	228.6 mm (0.25 vd)	10	4:1
1 yd	(0.25 ya)	1	4:1

⁰¹⁾ For gear ratio 4:1 models, when the side wheels rotate 4 times, the encoder rotates once.

Sold Separately: M17 Connector Cable

 \bullet For more information, refer to the M17 Connector Cable Product Manual.

Appearance	Power supply	Connector 1	Connector 2	Length	Model
	DC	M17 (Socket- Female) 6-pin	6-wire	2 m	CID6S-2
				5 m	CID6S-5
				10 m	CID6S-10
				15 m	CID6S-15