

# 2D Laser Scanners



## LSE Series PRODUCT MANUAL

**For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.**

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

### Major Features

- Monitoring zone up to 90°, 5.6 × 5.6 m
- Supports up to 4 channels
- Small size (W 125 × H 80.3 × L 88 mm) suitable for various installation environments
- Ethernet communication support
- atLiDAR, PC-only software support

### Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ⚠ symbol indicates caution due to special circumstances in which hazards may occur.

**⚠ Warning** Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)**  
Failure to follow this instruction may result in economic loss, personal injury or fire.
- 02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.**  
Failure to follow this instruction may result in fire or explosion.
- 03. This product is not safety sensor and does not observe any domestic nor international safety standard.**  
**Do not use this product with the purpose of injury prevention or life protection, as well as in the place where economic loss may be expected.**
- 04. Do not connect, repair, or inspect the unit while connected to a power source.**  
Failure to follow this instruction may result in fire.
- 05. Check connections and connect cables.**  
Failure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit.**  
Failure to follow this instruction may result in fire.

**⚠ Caution** Failure to follow instructions may result in injury or product damage.

- 01. Do not stare at the laser emitter.**  
Failure to follow this instruction may result in eye damage.
- 02. Use the unit within the rated specifications.**  
Failure to follow this instruction may result in fire or product damage.
- 03. Use dry cloth to clean the unit. Do not use water or organic solvent when cleaning the unit.**  
Failure to follow this instruction may result in fire.
- 04. Do not apply high pressure to the laser scanner to clean it.**

### Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- After supplying power, the sensor performs self-check for about 10 sec. When self-checking, error occurrence, remote control setting, and teaching, the laser scanner outputs the same as it sensed obstacle.
- Mutual optical interference between laser scanners and photoelectric sensors may result in malfunction.
- Mutual optical interference between laser scanners may result in malfunction.
- Objects cannot be scanned when covering the front cover of the laser scanner.
- When the laser scanner is moved to another position, use it after re-teaching (Teach-in).
- Do not drop the unit. It may cause malfunction.
- Installing the laser scanner in the place where smoke, fog, dust, or corrosion is heavy may result in malfunction.
- When installing the laser scanner outdoors, take protective measures. Otherwise, it may result in product damage.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case of installing power line and input signal line closely, use line filter or varistor at power line and shield wire at input signal line.
- Do not use the laser scanner near the equipment which generates strong magnetic force or high frequency noise.

- Cover with shields, hoods, or etc. to prevent direct incidence of strong light (direct rays of sunlight, incandescent) into the laser scanner beam spread angle.
- When fastening the laser scanner with the bracket, align with the mark line.
- When mounting the bracket onto an external object, remove the wire fixture so that the wire of the laser scanner is not pressed.
- Fix the laser scanner in position with the fixing screw. Vibration may result in malfunction.
- When IP address of the laser scanner and wireless router is same, the communication does not connected. Set the wireless network (Wifi) to "Disable" in the network settings of the Windows operating system.
- This unit may be used in the following environments.
  - Indoors / Outdoors (in the environment condition rated in 'Specifications')
  - Altitude max. 2,000 m
  - Pollution degree 2
  - Installation category II

## Product Components

- Product
- Instruction manual
- 3 mm allen wrench × 1
- Bracket × 1
- M2.6 × L6 Tapping screw × 2

## Software

Download the installation file and the manuals from the Autonics website.

### ■ atLiDAR

atLiDAR is the management program for laser scanner installation, parameter settings, status information and monitoring data, etc.  
This program communicates with the laser scanner via Ethernet communication.

## Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.  
Download the manuals from the Autonics website.

## Sold Separately

- Remote control: RMC-LS

## Network Setting

The laser scanner must be set identical with PC Network setting.

- Go to "Start > Control Panel > Network and Sharing Center > Change adapter settings > Ethernet > Properties".  
Double click "Internet Protocol Version 4 (TCP/IPv4) > Properties".
- [Advanced] > Click the [Add] button of IP Address and add the laser scanner IP address.

|             |                              |
|-------------|------------------------------|
| IP address  | 192.168.0.3 to 192.168.0.254 |
| Subnet mask | 255.255.255.0                |

## Order of Installation

For more information, refer to the atLiDAR software manual.

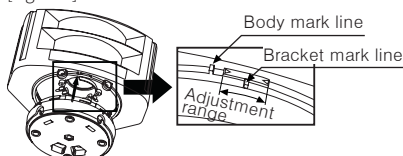
### 01. Install the laser scanner.

- Fix the bracket to the installation position using 4 hex socket bolts of above 5 mm.
- Pass the power, I / O and Ethernet cable through the holes in the bracket.
- After aligning one of the three indicator lines between the wrench holes on the side of the bracket with the indicator line on the main body, turn CW direction to be fixed. Rotate only within the adjustment range (-5 to 5°).

Refer to [Figure 1].

- Fix the hole in the bottom front of the main body to the bracket using M2.6 × L6 Tapping screw and screw driver.
- Adjust the bracket thilt angle (-3 to 3°) depending on the situation with a hexagon wrench in the wrench hole on the side of the bracket.

[Figure 1]



### 02. Install the laser scanner program, atLiDAR, to PC.

Download the software provided by Autonics website.

### 03. Connect the laser scanner and the PC, and set the network.

Refer to the Network Setting.

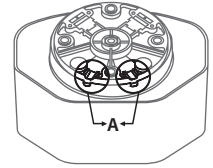
### 04. Laser scanner function setting

Use atLiDAR or remote controller, set each function to adequate the installation environment of the laser scanner and the obstacles to be detected.

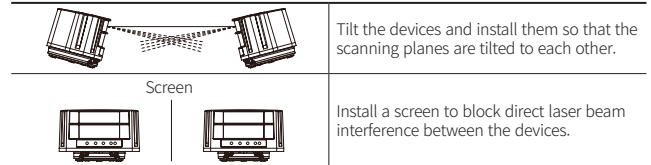
## Cautions for Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Impact with hard objects or excessive bending of the wire lead-out may result in damage on the waterproof function.
- Please use after testing. Check if the indicator is working properly depending on whether the obstacle exists.
- In case of insufficient space between the cable and the mounting surface, excessive force may be applied on the cable.

The part **A** may require to be cut if necessary.  
**⚠ Caution: When using the tools, be careful not to be wounded.**

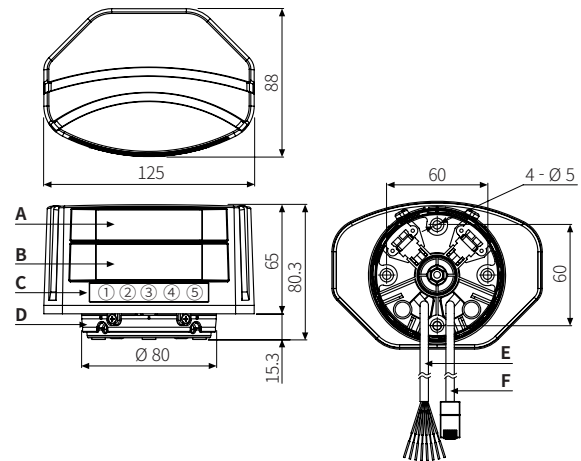


- To prevent mutual interference when installing multiple devices, refer to the below.



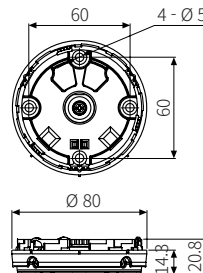
## Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.



|          |                |          |            |          |                    |
|----------|----------------|----------|------------|----------|--------------------|
| <b>A</b> | Laser emitter  | <b>C</b> | Indicators | <b>E</b> | Power, I / O cable |
| <b>B</b> | Laser receiver | <b>D</b> | Bracket    | <b>F</b> | Ethernet cable     |

### ■ Bracket



## Connections

### ■ Power, I / O cable

| Color  | Signal | Function                  |
|--------|--------|---------------------------|
| Brown  | +V     | +V                        |
| Blue   | GND    | GND                       |
| Yellow | OUT1_A | Obstacle detection output |
| Green  | OUT1_B |                           |
| Red    | OUT2_A | Error status output       |
| Gray   | OUT2_B |                           |
| Black  | IN_A   | Output test mode          |
| White  | IN_B   |                           |

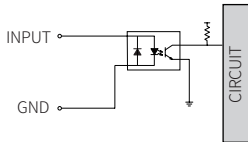
### ■ Ethernet cable

| Pin | Signal |
|-----|--------|
| 1   | TX+    |
| 2   | TX-    |
| 3   | RX+    |
| 4   | -      |
| 5   | -      |
| 6   | RX-    |
| 7   | -      |
| 8   | -      |

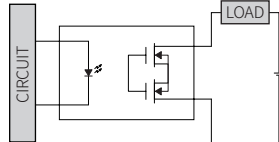
- The input / output signals can operate in both direction regardless of the polarity.
- When the photocoupler input is not used, do not wire both end of input terminal, or supply power under 3 VDC.

## Circuit

### ■ Photocoupler input



### ■ PhotoMOS relay output



## Specifications

|  |  |
|--|--|
| <b>Model</b>   | <b>LSE-4A5R2</b>   |
| <b>Emitting property</b>                               | Infrared laser   |
| Laser class  | CLASS 1  |
| Wave length band                                       | 905 nm   |
| Max. pulse output power                                | 75 W   |
| <b>Response time</b>                                   | Typ. 20 to 80 ms + monitoring time   |
| <b>Scanning mode</b>                                   | Motion and presence  |
| <b>Monitoring zone</b>                                 | 0.3 × 0.3 m to 5.6 × 5.6 m <sup>01)</sup>  |
| <b>Front contamination</b>                             | Normal operation with max. 30 % contamination of one material  |
| <b>Min. size of the scanning target</b> <sup>02)</sup> | At detection distance of 3 m: ≈ W 2.1 × H 2.1 × L 2.1 cm<br>At detection distance of 5 m: ≈ W 3.5 × H 3.5 × L 3.5 cm |
| <b>Angular resolution</b>                              | 0.4°   |
| <b>Aperture angle</b>                                  | 90°  |
| <b>Object reflectivity</b>                             | ≥ 2 %  |
| <b>Laser scanner angle</b>                             | -45°, 0°, 45°  |
| <b>Bracket rotation angle</b> <sup>03)</sup>           | -5 to 5°   |
| <b>Bracket tilt angle</b>                              | -3 to 3°   |
| <b>Life expectancy</b>                                 | ≤ 6.8 years  |
| <b>Approval</b>  | CE   |
| <b>Korean Railway Standards</b>                        | KRS SG 0068  |
| <b>Unit weight (package)</b>                           | ≈ 0.58 kg (≈ 0.96 kg)  |

01) At object reflectivity: 10 %

02) At object reflectivity: 90 % (Kodak Gray card R-27, White)

03) Indicates the laser scanner adjustment range.

|   |   |
|---|---|
| <b>Power supply</b>                       | 24 VDC± ± 20 %  |
| <b>Power consumption</b>                  | ≤ 8 W   |
| <b>Communication interface</b>            | Ethernet (TCP/IP) 10BASE-T  |
| <b>Input</b>                              | Photocoupler input<br>H <sup>01)</sup> : ≥ 8 - 30 VDC±, L: ≤ 3 VDC±   |
| <b>Output</b>                             | PhotoMOS relay output<br>Galvanic isolation, non-polarity<br>Resistive load: 30 VDC± / 24 VAC~, ≤ 80 mA<br>Output resistance: 30 Ω<br>Switching time: t <sub>ON</sub> = 5 ms, t <sub>OFF</sub> = 5 ms |
| <b>Insulation resistance</b>              | ≥ 5 MΩ (500 VDC± megger)  |
| <b>Dielectric strength</b>                | 500 VAC ~ 50 / 60 Hz for 1 minute   |
| <b>Vibration</b>                          | ≤ 2 G (18.7 m/s <sup>2</sup> )  |
| <b>Shock</b>                              | 30 G / 18 ms  |
| <b>Ambient illuminance</b>                | Sunlight: ≤ 100,000 lx  |
| <b>Ambient temperature</b> <sup>02)</sup> | -30 to 60 °C (no freezing or condensation)  |
| <b>Ambient humidity</b>                   | 0 to 95 %RH, storage: 0 to 95 %RH (no freezing or condensation)   |
| <b>Protection structure</b>               | IP67 (IEC standard)   |
| <b>Cable spec.</b>                        | Power, I / O cable: Ø 5 mm, 8-wire, 5 m<br>Ethernet cable: Ø 5 mm, 4-wire, 3 m, shield cable, RJ45 connector  |
| <b>Wire spec.</b>                         | AWG26 (0.16 mm, 7-core), insulator outer diameter: Ø 1 mm   |
| <b>Material</b>                           | PC  |

01) Operates as output test mode and outputs obstacle detection output and error status output.

02) Ambient temperature in power supplied status is -30 to 60°C and in power cut status is -10 to 60°C.

## Indicators

| Indicators      | ① (green)           | ② (green) | ③ (green)                | ④ (red)   | ⑤ (orange) |
|-----------------|---------------------|-----------|--------------------------|-----------|------------|
| <b>Function</b> | Ethernet connection | Power     | Remote control operation | Operation | Error      |

• The operation of indicator not stated in the description is unrelated with the status.

### ■ Indicator by situation

| Status                    | Indicator |                                    |     |                                    |     |
|---------------------------|-----------|------------------------------------|-----|------------------------------------|-----|
|                           | ①         | ②                                  | ③   | ④                                  | ⑤   |
| Comm. cable connection    | ON        | -                                  | -   | -                                  | -   |
| Scanning waiting sequence | 1         | -                                  | OFF | -                                  | ON  |
|                           | 2         | -                                  | OFF | ON                                 | -   |
|                           | 3         | -                                  | OFF | ON                                 | -   |
|                           | 4         | -                                  | OFF | Flashing (twice in every 0.5 sec)  | -   |
| Scanning                  | -         | Flashing (every 1 sec)             | OFF | -                                  | OFF |
| Obstacle detection        | -         | Flashing (every 1 sec)             | OFF | ON                                 | OFF |
| Teaching                  | -         | Flashing (every 1 sec, for 35 sec) | OFF | Flashing (every 1 sec, for 35 sec) | OFF |
| Output test mode          | -         | Flashing (every 0.05 sec)          | OFF | -                                  | OFF |

### ■ Error indicator

| Status                           | Indicator |   |   |   |                                     |
|----------------------------------|-----------|---|---|---|-------------------------------------|
|                                  | ①         | ② | ③ | ④ | ⑤                                   |
| Voltage error <sup>01)</sup>     | 1         | - | - | - | Flashing (3 times in every 0.2 sec) |
|                                  | 2         | - | - | - | Flashing (1 time in every 1 sec)    |
|                                  | 3         | - | - | - | OFF (2 sec)                         |
| Temperature error <sup>01)</sup> | 1         | - | - | - | Flashing (1 time in every 0.2 sec)  |
|                                  | 2         | - | - | - | Flashing (3 times in every 1 sec)   |
|                                  | 3         | - | - | - | OFF (2 sec)                         |

01) Repeat 1 to 3 step.

### ■ Remote control input key waiting

| Status   | Indicator |     |                           |     |     |
|----------|-----------|-----|---------------------------|-----|-----|
|          | ①         | ②   | ③                         | ④   | ⑤   |
| Password | -         | OFF | Flashing (every 0.05 sec) | OFF | OFF |
| Menu     | -         | OFF | Flashing (every 0.3 sec)  | OFF | OFF |
| Number   | -         | OFF | Flashing (every 0.05 sec) | OFF | OFF |

## Control Input / Output Status

| Output<br>Input | OUT1<br>(obstacle detection output) | OUT2<br>(error status output) |
|-----------------|-------------------------------------|-------------------------------|
| ON              | ON                                  | ON                            |
| OFF             | ON                                  | ON                            |
|                 | OFF                                 | OFF                           |
|                 | OFF                                 | OFF                           |

• Obstacle detection

• Teaching

• Error status

• Scanning ready

• Obstacle non-detection

• Error status

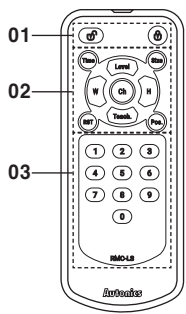
• Scanning ready

• Normal status

## Sold Separately: Remote Control

### RMC-LS

Each function can be set by the combination of the menu keys and the number keys. Refer to "Function Setting: Remote Control".



#### 01. UN-LOCK / LOCK

#### 02. Menu key

Time: Monitoring time  
Size: Scanning target size  
RST: Initialization to factory default  
Pos.: Sensor position  
Ch: Activated channel (s)  
Level: Sensitivity  
W: Width of the monitoring zone or concentrated monitoring zone  
H: Height of the monitoring zone or concentrated monitoring zone  
Teach.: Teaching

#### 03. Number key

## Function Setting: Remote Control

Initial entry differs depending on whether a password is set. This description is for the password not set.

- Password is not set: (F) (F)
- Password is set: (F) > Password
- If any key is not entered for 1 min after entering the (F) key, the laser scanner is scanning mode.

### Sensor position

(F) > Pos. > Number key setting > (F) twice

Set the view and mounting position based on the view of the main body in the detection area.

- e.g.) If the user sees the top of the laser scanner and is installed on the left, Set Top view + Left position.

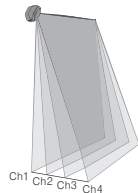
| Number key | SV     |                        |
|------------|--------|------------------------|
|            | View   | Position               |
| 0          |        | Center                 |
| 1          | Bottom | Left (factory default) |
| 2          |        | Right                  |
| 3          |        | Center                 |
| 4          | Top    | Left                   |
| 5          |        | Right                  |

### Activated channel (s)

(F) > Ch > (Each channel: Ch1 to Ch4) Number key setting > (F) twice

The laser scanner has 4 channels (Ch1, Ch2, Ch3, Ch4). Activate the channel (s) for obstacle detection.

| Number key | SV                          |
|------------|-----------------------------|
| 0          | Not activated               |
| 1          | Activated (factory default) |



### Monitoring zone: W (width) × H (height)

(F) > W (width) or H (height) > 0 > All Chs (0) or Select the set Ch (1 to 4) > Number key setting > (F) twice

If the mounting position is on left-right, set the width and height of the detection range for each channel. (it can be set in 0.1 m increments.)

If the mounting position is in the center, the detection range W (width) × H (height) = 5.6 × 5.6 m is fixed.

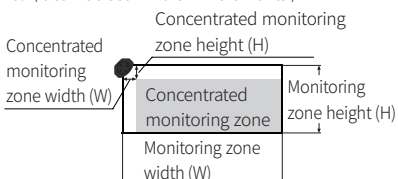
| Number key | SV           | Factory default |
|------------|--------------|-----------------|
| 05 to 60   | 0.5 to 6.0 m | 6.0 m           |

### Concentrated monitoring zone

(F) > W (width) or H (height) > 1 > All Chs (0) or Select the set Ch (1 to 4) > Number key setting > (F) twice

If the mounting position is on the left-right, set the unnecessary area to exclude from the obstacle area for each channel. (it can be set in 10 cm increments.)

| Number key | SV                    |  |
|------------|-----------------------|--|
| 0          | OFF (factory default) |  |
| 1          | 10 cm                 |  |
| 2          | 20 cm                 |  |
| 3          | 30 cm                 |  |



### Sensitivity level

(F) > Level > Number key setting > (F) twice

Set the object detection sensitivity of laser scanner.

| Number key | SV                               | Description   |
|------------|----------------------------------|---|
| 1          | Most sensitive (factory default) | Indoor installation                                 |
| 2          | Sensitive                        | -   |
| 3          | Insensitive                      | -   |
| 4          | Most insensitive                 | Installation in snow and rain environment available |

### Minimum size of the scanning target

(F) > Size > Number key setting > (F) twice

Set the size of minimum detection object.

- e.g.) Detecting the object over W 5 × H 5 × L 5 cm, set as 5 cm.

| Number key | SV                       |
|------------|--------------------------|
| 0          | OFF <sup>01)</sup>       |
| 1          | ≈ 5 cm (factory default) |
| 2          | ≈ 10 cm                  |
| 3          | ≈ 15 cm                  |
| 4          | ≈ 20 cm                  |

01) At detection distance of 3 m: detectable the objects over W 2.1 × H 2.1 × L 2.1 cm  
At detection distance of 5 m: detectable the objects over W 3.5 × H 3.5 × L 3.5 cm

### Monitoring time

(F) > Time > Number key setting > (F) twice

When an obstacle is scanned, obstacle detection output occurs after monitoring time. By setting monitoring time longer, the laser scanner scans monitoring zone repeatedly and scans obstacles without being affected by snow or rain. (it can be set in 100 ms incremental.)

| Number key | SV                       |
|------------|--------------------------|
| 0          | OFF                      |
| 1          | 100 ms (factory default) |
| 2          | 200 ms                   |
| ...        | ...                      |
| 9          | 900 ms                   |

### Output

(F) > RST > 4 > Number key setting > (F) twice

Set the output type between obstacle detection output (OUT 1) and error status output (OUT 2).

| Number key | SV                               |                                 |
|------------|----------------------------------|---------------------------------|
|            | Obstacle detection output (OUT1) | Error status output (OUT2)      |
| 0          |                                  | Normally open (factory default) |
| 1          | Normally open                    | Normally closed                 |
| 2          |                                  | Normally open                   |
| 3          | Normally closed                  | Normally closed                 |
| 4          | Normally open                    |                                 |
| 5          | Normally closed                  | Pulse                           |

### Teaching

(F) > Teach. > 0 (teaching) or 1 (initialization)

This function is to familiarize the space which is set by the monitoring zone width (W) and height (H) in advance. (Teaching takes 35 seconds.)

Objects within the detection range are not detected while teaching.

- Re-teach when the environment has been changed or objects are added or removed in same area.
- Operate teaching in the environment free from snow, rain, fog, hail, or mutual interference of another laser scanner.
- For re-install the unit teaching already at no teaching required area, initial the unit.

### Password

Set password: (F) > (F) > Password SV > (F) twice

Delete password: (F) > Password > Password > (F) > 7 > (F)

Restrict the access of settings by changing password. When setting password, the password function is activated. (Setting range: 0000 to 9999)

Please use the password function for preventing mutual interference of several units or malfunction.

- When losing the set password, re-supply the power and set the password again in 10 minutes.

### Factory default initialization

(F) > RST > 0

The laser scanner's settings and IP, except password initializes as factory default.

### IP initialization

(F) > RST > 1



























The laser scanner's IP address initializes as factory default.

## Checking SV













### > 9 > Keys for entering each function

The setting value can be checked through the remote controller and the indicator on the laser scanner for each function.

The indicator flashes as much as the value of the numeric keys. For more detailed setting value, refer to Function Setting: Remote Control.

| Function                                | Entering Key        | Indicator  |
|---|---------------------|--|
| Sensor position                         | Pos.                |  +  (flash)  |
| Activated channel (s)<br><sup>01)</sup> | Ch                  | Channels'  +  (flash)<br>Between Ch  +  +  +  (flash once)   |
| Monitoring zone <sup>02)</sup>          | W or H > 0 > Ch No. | Integer value  +  (flash)<br>Decimal point  +  +  +  (flash once)<br>Decimal value  +  (flash) |
| Concentrated monitoring zone            | W or H > 1 > Ch No. | Channels'  +  (flash)  |
| Sensitivity level                       | Level               |  +  (flash)  |
| Minimum size of the scanning target     | Size                |  +  (flash)  |
| Monitoring time                         | Time                |  +  (flash)  |
| Output                                  | RST > 4             |  +  (flash)  |

01) Activated Ch1, Ch3 and not activated Ch2, Ch4




 +  (flash once) >  +  +  +  (flash twice) >  +  (flash once) >  +  +  +  (flash once)

02) When checking the height after setting as W 3.4 × H 4.9 m

 +  (flash 4 times) >  +  +  +  (flash once) >  +  (flash 9 times)

## Troubleshooting

Check the normal operation status of laser scanner periodically.

| Error   | Causes   | Troubleshooting  |
|---|--|--|
| Power indicator<br>(  , green) OFF   | Supply the power voltage.<br>Wrong polarity connection of power supply   | Check the rated power supply.<br>Check the Connection diagram when wiring the unit.  |
| Error indicator<br>(  , orange) flashing                                  | Voltage error<br>Temperature error<br>Inside error   | Use the unit within the rated voltage.<br>Use the unit within the specified ambient temperature.<br>Contact the seller.  |
| Relay output is ON without objects within teaching area   | Detection by external environment (snow, rain, or hail, etc.)<br>There is the equipment which generates strong magnetic force or high frequency noise (motor, generator, or power cable, etc.) near the laser scanner. | Change the settings: sensitivity level, scanning target size, monitoring time.<br>Install the laser scanner away from the equipment which generates strong magnetic force or high frequency noise.                     |
| Laser scanner does not react for remote control operation.  | The batteries' life cycle of the remote control is over.<br>Wrong direction control of the remote control  | Change the batteries.<br>Operate the remote control towards the near laser scanner.  |
| After pressing the  key of remote control, the setting is not available. | Password incorrect.  | Turn OFF the power and re-supply the power, the password is available to reset.<br>Contact the seller.   |
| atLiDAR (PC program) and the laser scanner does not connected.  | LAN connector connection error<br>IP address is not same.<br>IP address of the laser scanner and wireless router is same.  | Check the PC and LAN connector connection part.<br>Check the IP address of the laser scanner and the user PC.<br>Set the wireless network (Wifi) to "Disable" in the network settings of the Windows operating system. |